

A Faster R CNN-based Real-time QRS Detector

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Abstract

Accurate QRS location keeps challenging in dynamic electrocardiograms (ECGs). Anti-interference abilities of the most existing QRS detectors need to be improved. This study addressed this issue and developed a novel faster R convolutional neural network (CNN) model-based real-time QRS detection algorithm. Firstly, ECGs were segmented into 10-s length episodes, and each episode was transformed into a 2-D image with a pixel size of 200 × 200 (VOC2007 format). Labelled QRS location information was used to generate the QRS bounding boxes in the images. A faster R CNN model was constructed. Candidates of QRS bounding boxes were extracted by the region proposal networks (RPN). Then, the boxes with small probabilities were excluded according to the rules of probability distribution and QRS location relationship. Finally, locations of QRS complexes were determined based on the geometric features and threshold rule.

The proposed algorithm was trained on the MIT/BIH arrhythmia database and verified on the actually recorded 24-h wearable ECGs. Five-fold cross validation on the MIT/BIH arrhythmia database achieved a sensitivity of 99.24% and a positive predictivity of 99.90%, resulting in an accuracy of 99.14%. When tested on 24-h wearable ECG recordings from 20 subjects, the algorithm generated a sensitivity of 98.76%, a positive predictivity of 98.52% and an accuracy of 97.32% compared to the manual annotations. In addition, the cost time of the new algorithm for processing a 10-s ECG episode was less than 20 ms under the experiments of CPU i7-2600 3.40 GHz, 8 GB RAM, tesla M60 GPU and 16 GB graphics memory.

1. Introduction

Electrocardiogram (ECG) is a comprehensive manifestation of cardiac electrophysiological activity, providing important information about the state of cardiac function [1]. Therefore, automatic diagnosis of static or long-term dynamic ECG is essential for doctors and patients. The accurate QRS recognition algorithm is the basis for automatic ECG analysis, which is important for the prevention and diagnosis of heart diseases [2, 3].

However, QRS detection in dynamic ECG, especially in wearable ECG, has encountered significant challenges due to motion disturbances, ECG electrode contact and myoelectric noise [4]. QRS detectors must be able to correctly detect different forms of QRS with large amounts of noise. However, the anti-noise and anti-interference ability of existing QRS detection algorithms is not strong enough [5, 6].

In general, in order to accurately identify the QRS complex, it is necessary to effectively pre-process the original ECG, which can suppress power frequency interference, myoelectric interference, respiratory interference and baseline noise, and help identify QRS complexes [7], such as Pan-Tompkins algorithm [8]. Kim and Shin [9] developed spatiotemporal characteristic-based detector, where the maximum energy level within the 5–25 Hz frequency band was accepted to belong to QRS complexes. Christov's QRS detector [10] used the information from more than one simultaneously recorded channels, with three special threshold rules: adaptive slew-rate, correction depending on the presence of high-frequency noise and low amplitude QRS complexes [11].

Although various QRS detectors have been developed, their anti-interference and anti-distortion abilities still need to be improved, especially when considering to combine some machine learning methods. This paper proposes a faster R convolutional neural network (CNN) model-based real-time QRS detector to address this problem.

2. Methods

2.1. Data

MIT/BIH arrhythmia database was used as training dataset. Wearable ECG data collected from a portable ECG device was used as test dataset, which included the 24-h ECGs from 20 patients with different arrhythmia types. All collected wearable ECG data were labeled by two independent cardiologists and arbitrated by a third.

2.2. Generation of QRS region of interest

To apply the fast R CNN model, ECG signal has to be

transformed into 2-D images. Firstly, ECG signals were segmented into 10-s segments. Secondly, in order to remove baseline drift and power frequency interference, a 0.5-40 Hz band pass filter was applied to the 10-s ECG segments. Thirdly, normalization was applied to normalize the ECG amplitude within the range of 0 and 1, which can eliminate the adverse effects caused by the abnormal noises. Then, 1-D data was transformed into 200×200 pictures through the matplotlib tools in Python. Finally, since the width of the QRS is usually about 120 ms, the rectangular range of the QRS complex was limited 100 ms forward and 100 ms backward at the position of R peak. Fig. 1 shows the process of generating ECG image datasets. Fig. 2 demonstrates an example of QRS bounding boxes in the ECG image.

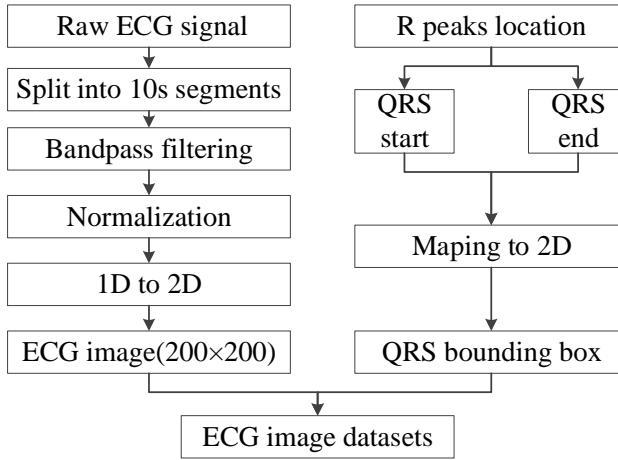


Figure 1. Generation of ECG samples for the faster R CNN-based QRS detector.

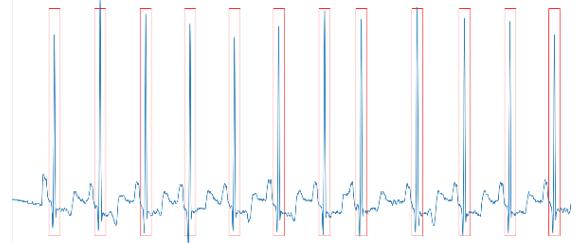


Figure 2. An example of QRS bounding boxes (red rectangles) within a 10-s ECG segment.

2.3. Faster R CNN Model

As shown in Fig. 3, a 10-s ECG 2-D image (200×200) was first put into the feature extraction network of VGG16, which included 13 convolution layers, 13 rectified linear units (RELU) layers and 4 pooling layers. Then the feature maps were put into a regional proposal networks (RPN) network [12], which included two branches. The top branch obtained foreground (QRS region of interest (ROI)) and background by the softmax function. The low branch calculated bounding box regression offset to get accurate proposals [13]. ROI pooling layer mapped the proposals to the feature map and resized these regions into same size sections by max pooling operation [12]. The classifier layers got the precise locations of QRS complexes by the fully connected layers and softmax function.

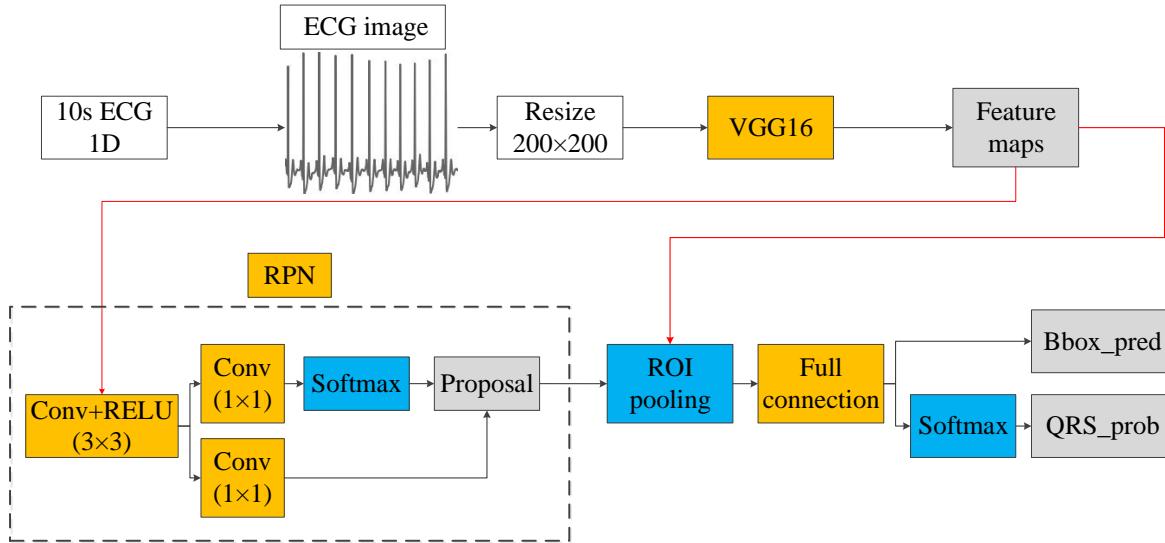


Figure 3. Model structure of the proposed faster R CNN-based QRS detector. VGG16 is used for feature extraction, RPN layer is used to select candidate targets, ROI pooling layer maps the proposals to the feature map.

2.4. Parameter setting

Before training, we need to pre-set several parameters. The loss function of fast R-CNN is set as:

$$L(\{p_i\}, \{t_i\}) = \frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*) + \gamma \frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*). \quad (1)$$

where $t_i = \{t_x, t_y, t_w, t_h\}$ is a vector representing anchor's predicted offset, t_i^* is the same one-dimensional vector as t_i , representing the actual offset of anchor relative to ground truth, p_i is the probability of anchor prediction, and p_i^* represents the ground truth.

There are two parts in formula (1), the first part is the classification loss and the second part is bounding box regression loss. Classification loss is cross-entropy loss function, which means calculating logarithmic loss for each anchor and dividing the sum by the total number of anchors $\frac{1}{N_{cls}}$. Usually, $f(x) = x^2$ is chosen in Bounding box regression. However, this loss function will be very high if large errors are encountered [14]. Therefore, slightly flat absolute loss function, i.e., $f(x) = |x|$, is applied herein, which increases linearly with the error rather than squarely. The derivative of this function does not exist at 0, which has a bad influence on the convergence of functions. Piecewise function is introduced to make it smoother by using square function near 0, named smooth L1 loss function. In this study, the smooth L1 loss function is defined by

$$\text{smooth}_{L1}(x) = \begin{cases} 0.5x^2 \times \frac{1}{\sigma^2}, & \text{if } |x| < \frac{1}{\sigma^2}, \\ |x| - 0.5, & \text{otherwise} \end{cases} \quad (2)$$

where x represents the difference between the actual offset of the border and the predicted offset $x = t_i - t_i^*$ and $\sigma = 3$. Learning rate was set 0.001, Gradient descent method with momentum was chosen as optimization method.

2.5. QRS location with the model output

ROI of QRS information can be obtained by the proposed fast R-CNN Model. As is shown in Fig. 2, the R peaks are located inside the red rectangles. The slope of QRS is the most obvious feature [15]. In order to extract the location of QRS more accurately, the bilateral slope method was used to precisely locate the position of R peaks:

$$\text{slop}L_i = \text{ecg}_i - \text{ecg}_{i-4}, \quad (3)$$

$$\text{slop}R_i = \text{ecg}_i - \text{ecg}_{i+4}, \quad (4)$$

where $\text{slop}L_i$ and $\text{slop}R_i$ indicate the left and right slopes, respectively, ecg_i represents the ECG amplitude.

3. Results and discussion

Five-fold cross validation on the MIT/BIH arrhythmia database achieved a sensitivity (Se) of 99.24% and a positive predictivity ($+P$) of 99.90%, resulting in an accuracy (Acc) of 99.14%, as shown in table 1. When tested on the twenty 24-h wearable ECG recordings, the algorithm generated a Se of 98.76%, a $+P$ of 98.52% and an Acc of 97.32% compared to the manual annotations.

From Tables 1 and 2, we can see that the proposed fast R-CNN algorithm can well perform the QRS detection task.

Although trained on the MIT/BIH arrhythmia database, the QRS detector can still have a good performance on wearable ECG data, which shows a strong generalization ability.

Table 1. Five-fold cross validation results on the MIT/BIH arrhythmia database.

Fold	TP	FP	FN	Se (%)	+P (%)	Acc (%)
1	19059	64	78	99.59	99.67	99.26
2	18916	7	131	99.31	99.96	99.28
3	21542	21	257	98.82	99.9	98.73
4	26449	2	195	99.27	99.99	99.26
5	20823	10	164	99.22	99.95	99.17
Mean	/	/	/	99.24	99.90	99.14
SD	/	/	/	0.08	0.02	0.05

Table 2. Results of the proposed QRS detector on the twenty 24-h wearable ECG recordings.

#subject	TP	FP	FN	Se (%)	+P (%)	Acc (%)
1	132957	1229	624	99.53	99.08	98.63
2	100345	392	542	99.46	99.61	99.08
3	73028	1664	312	99.57	97.77	97.37
4	98905	1383	906	99.09	98.62	97.74
5	133725	793	3907	97.16	99.41	96.60
6	97811	1417	2492	97.52	98.57	96.16
7	115364	58	540	99.53	99.95	99.48
8	67346	1698	958	98.60	97.54	96.21
9	77003	1097	625	99.19	98.60	97.81
10	107291	1624	1288	98.81	98.51	97.36
11	110539	4653	1943	98.27	95.96	94.37
12	79257	2061	488	99.39	97.47	96.88
13	97228	255	217	99.78	99.74	99.52
14	108798	448	992	99.10	99.59	98.69
15	97133	1356	1682	98.30	98.62	96.97
16	71810	3213	1497	97.96	95.72	93.84
17	86631	677	689	99.21	99.22	98.45
18	70608	1308	1118	98.44	98.18	96.68
19	114731	893	2164	98.15	99.23	97.40
20	110933	1047	2140	98.11	99.07	97.21
Mean	/	/	/	98.76	98.52	97.32
SD	/	/	/	0.55	1.34	2.24

We also tested the calculation cost. The cost time of the new algorithm for processing a 10-s ECG episode was less than 20 ms under the experiments of CPU i7-2600 3.40 GHz, 8 GB RAM, tesla M60 GPU and 16 GB graphics memory. The new QRS detector should be carried out on

GPU, and thus the resource consumption is large. It still needs to be optimized in resource consumption to facilitate the practical use in the future.

Traditional QRS detection methods are usually affected by noise and QRS shape, which is hard to improve $+P$ and Se simultaneously. In the contrary, the new QRS detector can deal with the QRS detection under different noise situation, generating an increase of $+P$ and Se simultaneously. In addition, the proposed method can not only used for QRS detection, but also has potential for other feature identification, such as T waves, P waves.

4. Conclusion

This study presents an effective QRS detection method based on Fast R CNN model, which generated a sensitivity of 98.76%, a positive predictivity of 98.52% and an accuracy of 97.32% on the actually collected twenty 24-h wearable ECG recordings. It is only a pilot study, and more work need to further improve the issue of resource consumption.

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